

# **Solution Manual Digital Control System Nagle**

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(b)  $13 \ 2 \ 3 \ 13 \ () \ () \ () \ 1 \ () \ C_s \ G_s G \ s \ G \ s G \ s R_s \ G \ s G \ s H_s +$   
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 $s H \ s = + +$  1.1-4. A feedback control system is  
illustrated in Fig. P1.1-4. The plant transfer function is  
given by  $G_p(s) = \frac{5}{0.2s + 1}$   $G_c(s)$   $G_p(s)$  Compensator  
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